

1. Below, you are given the augmented matrix corresponding to a linear system of equations, together with the reduced row-echelon form of that augmented matrix:

$$(A | \mathbf{b}) = \left(\begin{array}{ccc|c} 0 & 1 & -2 & 3 \\ 2 & -3 & 1 & 0 \\ 4 & -7 & 4 & -3 \\ -6 & 13 & -11 & 12 \end{array} \right) \xrightarrow{\text{row ops}} \left(\begin{array}{ccc|c} 1 & 0 & \frac{-5}{2} & \frac{9}{2} \\ 0 & 1 & -2 & 3 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right) = \text{rref}(A | \mathbf{b})$$

- (a) Write down the system of linear equations which correspond to the original matrix.
- (b) Solve the system $A\mathbf{x} = \mathbf{b}$.
- (c) Find a basis for the column space of A .
- (d) Is \mathbf{b} in the span of the columns of A ? Why or why not?
- (e) Find a basis for the null space of A .
2. Suppose that data obtained in an experiment is supposed to fit a model of the form

$$z = a + bx + cx^2 + dy$$

where a, b, c and d are constants.

- (a) Set up a linear system which can be used to solve for a, b, c and d if the data points (of the form (x, y, z)) obtained are $(2, 1, 5)$, $(-3, 1, 2)$, $(-2, 0, 2)$, $(1, 4, 3)$ and $(3, 5, 10)$. In particular, what are A , \mathbf{x} and \mathbf{b} ?
- (b) Write down the formula (in terms of A , \mathbf{x} and/or \mathbf{b}) which computes the least-squares solution $\hat{\mathbf{x}}$. (You do not actually have to compute $\hat{\mathbf{x}}$.)
3. (a) If $\mathbf{v} = (2, -1, 5)$ and $\mathbf{w} = (0, 1, -2)$, compute $2\mathbf{v} - \mathbf{w}$.
- (b) Compute $(3, -1, 4) \cdot (2, 0, -5)$.
- (c) Compute the projection of $(-11, 3)$ onto $(2, 7)$.
- (d) Compute the distance between the vectors $(2, -1, 4, 3)$ and $(-4, 0, 7, -1)$.
4. (a) Find the transpose of the matrix $\begin{pmatrix} 1 & 2 & 0 & 1 \\ 0 & 1 & -2 & 4 \end{pmatrix}$.
- (b) Find AB if $A = \begin{pmatrix} 1 & -3 \\ 2 & 1 \end{pmatrix}$ and $B = \begin{pmatrix} 3 & 0 & 1 \\ -2 & 5 & 3 \end{pmatrix}$.
- (c) Find the inverse of the matrix $\begin{pmatrix} 8 & -5 \\ -4 & 3 \end{pmatrix}$.
- (d) Find the determinant of the matrix $\begin{pmatrix} 2 & -5 & 1 \\ 0 & 4 & -1 \\ -3 & 3 & 2 \end{pmatrix}$.

5. Let $A = \begin{pmatrix} 3 & 4 \\ 1 & 6 \end{pmatrix}$.

- (a) Compute the exact value of A^{3000} (show all your work).
 (b) Compute e^A .
6. (a) Find the point of intersection (if there is one) of the two lines in \mathbb{R}^3 whose parametric equations are

$$\begin{cases} x = 3t \\ y = 1 + 2t \\ z = -1 - t \end{cases} \quad \begin{cases} x = -2 + 4t \\ y = 7 - t \\ z = -3 + t \end{cases}$$

- (b) Write the normal equation of the plane in \mathbb{R}^3 whose parametric equations are

$$\begin{cases} x = -1 + 2s - 3t \\ y = 1 - s + t \\ z = 3 - 3s + 5t \end{cases} .$$

7. Suppose:

- A is an invertible 3×3 matrix;
- B is a 3×4 matrix;
- C is a 4×3 matrix;
- D is a 1×3 matrix;
- $\mathbf{x}, \mathbf{y}, \mathbf{z}$ are vectors in \mathbb{R}^3 ;
- \mathbf{v} and \mathbf{w} are vectors in \mathbb{R}^4 ; and
- k, l and m are scalars.

Determine whether the following expressions are a **matrix** (in which you should give its size), a **vector** (in which case you should give the vector space to which the vector belongs), a **scalar**, or **nonsense**:

- | | |
|---|---|
| (a) $tr(A)$ | (g) $kB^T A^{-1}m$ |
| (b) $\mathbf{v} \cdot (\mathbf{vw})$ | (h) $(D\mathbf{x})A^2(\mathbf{z} + 3k\mathbf{y})$ |
| (c) $\mathbf{x} \times \mathbf{y}$ | (i) $\det(A)B$ |
| (d) $\mathbf{v} \times \mathbf{w}$ | (j) $\det(AB)$ |
| (e) $\ \mathbf{v} - \mathbf{w}\ \ \mathbf{x} + \mathbf{y}\ $ | (k) $D\mathbf{z}m$ |
| (f) $\ \mathbf{x}\ \mathbf{x}$ | (l) $m\mathbf{z}D$ |

8. Classify the following statements as true or false:
- (a) The vectors $(2, 1, -5)$ and $(3, 3, 2)$ are orthogonal.
 - (b) \mathbb{R}^4 is a four-dimensional subspace of \mathbb{R}^5 .
 - (c) The function $T : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ defined by $T(x, y) = (2x, x - y, x + y)$ is a linear transformation.
 - (d) The transformation $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ which projects vectors onto the y -axis is injective.
 - (e) The set of vectors lying on the plane $3x - 2y + 4z = 2$ is a subspace of \mathbb{R}^3 .
 - (f) The following set is linearly independent: $\{(1, 2, 1), (2, -5, 4), (3, -1, 2), (4, 4, -7)\}$
 - (g) For square matrices A and B of the same size, $\det(A + B) = \det(A) + \det(B)$.
 - (h) If \mathbf{v} , \mathbf{w} and \mathbf{x} are in \mathbb{R}^n , then $\mathbf{v} \cdot (\mathbf{w} + \mathbf{x}) = \mathbf{v} \cdot \mathbf{w} + \mathbf{v} \cdot \mathbf{x}$.
 - (i) The vectors $(0, 0, 0, 0)$ and $(2, -3, 4, -1)$ are parallel.
 - (j) The transformation $T : C(\mathbb{R}, \mathbb{R}) \rightarrow \mathbb{R}$ defined by $T(f) = f(0)$ is a linear transformation.
9. Fill in the blank with the word “always”, “sometimes” or “never” to make the statement correct:
- (a) A 2×3 matrix is _____ diagonalizable.
 - (b) If $T : V_1 \rightarrow V_2$ and $S : V_2 \rightarrow V_3$ are linear transformations, then the composition $S \circ T$ is _____ linear.
 - (c) A system of 5 linear equations in 3 variables _____ has exactly one solution.
 - (d) $|\mathbf{v} \cdot \mathbf{w}|$ is _____ less than or equal to $\|\mathbf{v}\| \|\mathbf{w}\|$.
 - (e) The zero vector is _____ part of a basis.
 - (f) Given a set of three vectors in \mathbb{R}^4 , that set _____ spans \mathbb{R}^4 .
 - (g) Given a set of four vectors in \mathbb{R}^4 , that set _____ spans \mathbb{R}^4 .
 - (h) Given a set of five vectors in \mathbb{R}^4 , that set _____ spans \mathbb{R}^4 .
 - (i) A matrix with eigenvalue 0 is _____ invertible.
 - (j) A set of one nonzero vector is _____ linearly independent.
10. Answer the following questions:
- (a) If W is an eight-dimensional subspace of \mathbb{R}^{13} , what is the dimension of W^\perp ?
 - (b) If a 10×7 matrix has 5 linearly independent columns, what is the dimension of the null space of this matrix?
 - (c) If a 5×8 matrix is the matrix of a surjective linear transformation, what is the rank of the matrix?
 - (d) If the eigenvalues of a matrix are 2, 2, -3 and 1, what is the trace of the matrix?
 - (e) How many vectors are there in a basis of a three-dimensional subspace of \mathbb{R}^7 ?

1. (a) If you call the variables x, y and z the system is

$$\begin{cases} y - 2z = 3 \\ 2x - 3y + z = 0 \\ 4x - 7y + 4z = -3 \\ -6x + 13y - 11z = 12 \end{cases}$$

- (b) From the rref form, we see

$$\begin{cases} x - \frac{5}{2}z = \frac{9}{2} \\ y - 2z = 3 \end{cases} \Rightarrow \begin{cases} x = \frac{9}{2} + \frac{5}{2}z \\ y = 3 + 2z \end{cases}$$

Thus the solution set is

$$(x, y, z) = \left(\frac{9}{2} + \frac{5}{2}z, 3 + 2z, z\right) = \left(\frac{9}{2}, 3, 1\right) + z\left(\frac{5}{2}, 2, 1\right) = \left(\frac{9}{2}, 3, 1\right) + \text{Span}\left(\frac{5}{2}, 2, 1\right).$$

- (c) Such a basis consists of the pivot columns of A ; it is $\{(0, 2, 4, -6), (1, -3, -7, 13)\}$.
 (d) Yes, because $A\mathbf{x} = \mathbf{b}$ has at least one solution.
 (e) From the answer to (b), we see that since the solution is always of the form $\mathbf{x}_p + N(A)$, $N(A) = \text{Span}\left(\frac{5}{2}, 2, 1\right)$ so a basis for $N(A)$ is the single vector $\left(\frac{5}{2}, 2, 1\right)$.
2. (a) Plugging each point in for (x, y, z) , we obtain the system

$$\begin{cases} a + 2b + 4c + 1 = 5 \\ a - 3b + 9c + d = 2 \\ a - 2b + 4c = 2 \\ a + b + c + 4d = 3 \\ a + 3b + 9c + 5d = 10 \end{cases}$$

Therefore we are trying to solve $A\mathbf{x} = \mathbf{b}$ where

$$A = \begin{pmatrix} 1 & 2 & 4 & 1 \\ 1 & -3 & 9 & 1 \\ 1 & -2 & 4 & 0 \\ 1 & 1 & 1 & 4 \\ 1 & 3 & 9 & 5 \end{pmatrix}; \quad \mathbf{x} = \begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix}; \quad \mathbf{b} = \begin{pmatrix} 5 \\ 2 \\ 2 \\ 3 \\ 10 \end{pmatrix}.$$

Set up a linear system which can be used to solve for a, b, c and d if the data points (of the form (x, y, z)) obtained are $(2, 1, 5)$, $(-3, 1, 2)$, $(-2, 0, 2)$, $(1, 4, 3)$ and $(3, 5, 10)$. In particular, what are A , \mathbf{x} and \mathbf{b} ?

- (b) As always, $\hat{\mathbf{x}} = (A^T A)^{-1} A^T \mathbf{b}$.

3. (a) $2\mathbf{v} - \mathbf{w} = 2(2, -1, 5) - (0, 1, -2) = (4, -3, 12)$.
 (b) $(3, -1, 4) \cdot (2, 0, -5) = 3(2) - 1(0) + 4(-5) = 6 - 20 = -14$.
 (c) $\text{proj}_{(2,7)}(-11, 3) = \frac{(2,7) \cdot (-11,3)}{(2,7) \cdot (2,7)}(2, 7) = \frac{-1}{53}(2, 7) = \left(\frac{-2}{53}, \frac{-7}{53}\right)$.
 (d) $\|(2, -1, 4, 3) - (-4, 0, 7, -1)\| = \|(6, -1, -3, 4)\| = \sqrt{(6, -1, -3, 4) \cdot (6, -1, -3, 4)} = \sqrt{36 + 1 + 9 + 16} = \sqrt{62}$.

4. (a) $\begin{pmatrix} 1 & 2 & 0 & 1 \\ 0 & 1 & -2 & 4 \end{pmatrix}^T = \begin{pmatrix} 1 & 0 \\ 2 & 1 \\ 0 & -2 \\ 1 & 4 \end{pmatrix}$.

(b) $AB = \begin{pmatrix} 1(3) + (-3)(-2) & 1(0) - 3(5) & 1(1) - 3(3) \\ 2(3) - 2 & 2(0) + 5 & 2 + 3 \end{pmatrix} = \begin{pmatrix} 9 & -15 & -8 \\ 4 & 5 & 5 \end{pmatrix}$.

(c) $\begin{pmatrix} 8 & -5 \\ -4 & 3 \end{pmatrix}^{-1} = \frac{1}{8(3) - (-5)(-4)} \begin{pmatrix} 3 & 5 \\ 4 & 8 \end{pmatrix} = \frac{1}{4} \begin{pmatrix} 3 & 5 \\ 4 & 8 \end{pmatrix} = \begin{pmatrix} \frac{3}{4} & \frac{5}{4} \\ 1 & 2 \end{pmatrix}$.

- (d) Repeat the first two columns to the right of the matrix; multiply along the diagonals and then add/subtract to get

$$\det \begin{pmatrix} 2 & -5 & 1 \\ 0 & 4 & -1 \\ -3 & 3 & 2 \end{pmatrix} = 16 - 15 + 0 - (-12) - (-6) - 0 = 19.$$

5. (a) First, find the eigenvalues of A . $\det(A - \lambda I) = \det \begin{pmatrix} 3 - \lambda & 4 \\ 1 & 6 - \lambda \end{pmatrix} = (3 - \lambda)(6 - \lambda) - 4 = \lambda^2 - 9\lambda + 14 = (\lambda - 7)(\lambda - 2)$ so the eigenvalues are $\lambda = 2$ and $\lambda = 7$.

Next, eigenvectors: when $\lambda = 2$, $A\mathbf{x} = \lambda\mathbf{x}$ gives $3x + 4y = 2x$ and $x + 6y = 2y$, i.e. $x = -4y$, so an eigenvector is $(-4, 1)$. When $\lambda = 7$, $A\mathbf{x} = \lambda\mathbf{x}$ gives $3x + 4y = 7x$ and $x + 6y = 7y$, i.e. $x = y$, so an eigenvector is $(1, 1)$. Therefore

$$A = S\Lambda S^{-1} = \begin{pmatrix} -4 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 2 & 0 \\ 0 & 7 \end{pmatrix} \begin{pmatrix} -4 & 1 \\ 1 & 1 \end{pmatrix}^{-1}.$$

Now

$$\begin{aligned} A^{3000} &= S\Lambda^{3000}S^{-1} = \begin{pmatrix} -4 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 2^{3000} & 0 \\ 0 & 7^{3000} \end{pmatrix} \frac{1}{-5} \begin{pmatrix} 1 & -1 \\ -1 & -4 \end{pmatrix} \\ &= \frac{-1}{5} \begin{pmatrix} -4 \cdot 2^{3000} - 7^{3000} & 4 \cdot 2^{3000} - 4 \cdot 7^{3000} \\ 2^{3000} - 7^{3000} & -2^{3000} - 4 \cdot 7^{3000} \end{pmatrix}. \end{aligned}$$

- (b) Using much of the work from part (a),

$$\begin{aligned} e^A &= Se^{\Lambda}S^{-1} = \begin{pmatrix} -4 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} e^2 & 0 \\ 0 & e^7 \end{pmatrix} \frac{1}{-5} \begin{pmatrix} 1 & -1 \\ -1 & -4 \end{pmatrix} \\ &= \frac{-1}{5} \begin{pmatrix} -4 \cdot e^2 - e^7 & 4e^2 - 4e^7 \\ e^2 - e^7 & -e^2 - 4e^7 \end{pmatrix}. \end{aligned}$$

6. (a) We need to change the t in one equation to s , then solve for the intersection point. We get

$$\begin{cases} 3t = -2 + 4s \\ 1 + 2t = 7 - s \\ -1 - t = -3 + s \end{cases}$$

Solving the second equation for s , we get $s = 6 - 2t$. Plugging this into the third equation, we get $-1 - t = -3 + 6 - 2t$, i.e. $t = 4$ (so by back-substitution in the equation $x = 6 - 2t$, $s = -2$). These values of s and t work in the last two equations, but not in the first one, so these lines do not intersect.

- (b) Two direction vectors for the plane are $(2, -1, 3)$ and $(-3, 1, 5)$. To obtain a normal vector, take the cross product: $\mathbf{n} = (2, -1, 3) \times (-3, 1, 5) = (-8, -19, -1)$. One point on the plane is $(-1, 1, 3)$; set $d = \mathbf{n} \cdot (-1, 1, 3) = 8 - 19 - 3 = -14$. So the equation of the plane is $\mathbf{n} \cdot \mathbf{x} = d$, i.e. $-8x - 19y - z = -14$. (Any multiple of this equation is also a valid solution.)
7. (a) $\text{tr}(A)$ is the sum of the diagonal entries, which is a **scalar**.
 (b) \mathbf{vw} is nonsense, so the whole thing is **nonsense**.
 (c) $\mathbf{x} \times \mathbf{y}$ is a **vector** in \mathbb{R}^3 .
 (d) $\mathbf{v} \times \mathbf{w}$ is **nonsense** (there is no cross product of vectors in \mathbb{R}^4).
 (e) $\|\mathbf{v} - \mathbf{w}\| \|\mathbf{x} + \mathbf{y}\|$ is the product of two scalars, hence a **scalar**.
 (f) $\|\mathbf{x}\|\mathbf{x}$ is a scalar times a vector which is a **vector** in \mathbb{R}^3 .
 (g) $k(B^T)_{4 \times 3}(A^{-1})_{3 \times 3}m$ is a 4×3 **matrix**.
 (h) First, $\mathbf{z} + 3k\mathbf{y}$ is a vector in \mathbb{R}^3 . Next, $D\mathbf{x} = D_{1 \times 3}\mathbf{x}_{3 \times 1}$ is a 1×1 matrix, hence a scalar. Then $(D\mathbf{x})_{\text{scalar}}(A^2)_{3 \times 3}(\mathbf{z} + 3k\mathbf{y})_{3 \times 1}$ is a 3×1 matrix, i.e. a **vector** in \mathbb{R}^3 .
 (i) $\det(A)B$ is a scalar times a matrix which is a 3×4 **matrix**.
 (j) $\det(AB)$ is **nonsense** since nonsquare matrices do not have determinants.
 (k) $D_{1 \times 3}\mathbf{z}_{3 \times 1}m$ is a 1×1 matrix, i.e. a **scalar**.
 (l) $m\mathbf{z}_{3 \times 1}D_{1 \times 3}$ is a 3×3 **matrix**.

8. (a) $(2, 1, -5) \cdot (3, 3, 2) = 6 + 3 - 10 = -1 \neq 0$ so this is FALSE.
- (b) \mathbb{R}^4 consist of vectors with four components, but subspaces of \mathbb{R}^5 are sets of vectors with five components. Therefore this is FALSE.
- (c) You can check $T(\mathbf{x} + \mathbf{y}) = T(\mathbf{x}) + T(\mathbf{y})$ and $T(r\mathbf{x}) = rT(\mathbf{x})$ so this T is linear; the answer is TRUE.
- (d) $T(1, 0) = 0$ so $\ker(T) \neq \{\mathbf{0}\}$ so this transformation is not injective, so this statement is FALSE.
- (e) $\mathbf{0}$ is not in this set, so this statement is FALSE.
- (f) These are four vectors in the three-dimensional space \mathbb{R}^3 (i.e. too many to be lin. indep.), so this statement is FALSE.
- (g) If you try virtually any examples of matrices, you will see that this is FALSE.
- (h) This is a property of dot products; it is TRUE.
- (i) $\mathbf{0}$ is parallel to every vector, so this is TRUE.
- (j) Evaluation of a function is linear, so this is TRUE.
9. (a) A 2×3 matrix is NEVER diagonalizable (it isn't square).
- (b) If $T : V_1 \rightarrow V_2$ and $S : V_2 \rightarrow V_3$ are linear transformations, then the composition $S \circ T$ is ALWAYS linear (theorem from class).
- (c) A system of 5 linear equations in 3 variables SOMETIMES has exactly one solution (because the null space could have dimension 0 or dimension greater than 0).
- (d) $|\mathbf{v} \cdot \mathbf{w}|$ is ALWAYS less than or equal to $\|\mathbf{v}\| \|\mathbf{w}\|$ (this is the Cauchy-Schwarz Inequality).
- (e) The zero vector is NEVER part of a basis (it is never part of a lin. indep. set).
- (f) Given a set of three vectors in \mathbb{R}^4 , that set NEVER spans \mathbb{R}^4 (there aren't enough vectors to span).
- (g) Given a set of four vectors in \mathbb{R}^4 , that set SOMETIMES spans \mathbb{R}^4 (depending on what those vectors are).
- (h) Given a set of five vectors in \mathbb{R}^4 , that set SOMETIMES spans \mathbb{R}^4 (it depends on what those vectors are).
- (i) A matrix with eigenvalue 0 is NEVER invertible (because its determinant is the product of the eigenvalues which must be 0).
- (j) A set of one nonzero vector is ALWAYS linearly independent (fact from class).
10. (a) $\dim W^\perp = \dim \mathbb{R}^{13} - \dim W = 13 - 8 = 5$.
- (b) We have $m = 10$, $n = 7$ and $r = 5$. So $\dim N(A) = n - r = 2$.
- (c) If the transformation is surjective, we have $r = m = 5$.
- (d) The trace is the sum of the eigenvalues: $2 + 2 - 3 + 1 = 2$.
- (e) Since the dimension is 3, there are 3 vectors in any basis of that subspace.